## Supplement for "Stepwise Signal Extraction via Marginal Likelihood" by Du, Kao and Kou, Journal of the American Statistical Association

## Proofs for the Theoretical Results in Section 3

We use the following notations throughout the proofs. We denote the number of observations within a given interval as  $n_{(a,b]} = \#\{i : a < t_i \leq b, 1 \leq i \leq n\}$ , the associated likelihood function as  $p_{(a,b]}(\theta) = \prod_{t_i \in (a,b]} f(x_i|\theta)$ , and the corresponding log-likelihood  $l_{(a,b]}(\theta) = \log p_{(a,b]}(\theta)$ . The maximum likelihood estimator based on  $l_{(a,b]}$  is denoted as  $\hat{\theta}_{(a,b]}$ . In what follows, we present our proofs for one-dimensional  $\theta$ , but we want to emphasize that this is only for notational convenience. A general dimensional case can be easily obtained through a straightforward substitution of the one dimensional quantities with their multivariate counterparts. We denote  $\hat{\sigma}_{(a,b]}^2 = \{-l''_{(a,b]}(\hat{\theta}_{(a,b]})\}^{-1}$ , the observed Fisher information, and let  $J(\theta_0)$  represent the (expected) Fisher information evaluated at  $\theta_0$ . We use  $\xrightarrow{P}$  and  $o_p(1)$  to denote convergence in probability and  $O_p(1)$  to denote a sequence bounded in probability.

Next, we list the conditions (A1)-(A5) and (B1)-(B4) discussed in Section 3. Conditions (A1)-(A5) are used to ensure the consistency of the MLE of  $\theta_j$ . Conditions (B1)-(B4) ensure that the second derivative of log-likelihood is sufficiently smooth for values near  $\theta_j$ . See Walker (1969).

- (A1)  $\Theta$  is a closed set of points on the real line.
- (A2) The set of points  $\{x : f(x|\theta) > 0\}$  is independent of  $\theta$ ; we denote this set by  $\mathcal{X}$ .
- (A3) If  $\theta_1, \theta_2$  are two distinct points of  $\Theta$ , then the Lebegue measure of  $\mu\{x : f(x|\theta_1) \neq f(x|\theta_2)\} > 0$ .
- (A4) Let  $x \in \mathcal{X}$ ,  $\theta' \in \Theta$ . For all  $\theta$  such that  $|\theta \theta'| < \delta$  with  $\delta$  sufficiently small, we have  $|\log f(x|\theta) \log f(x|\theta')| < H_{\delta}(x,\theta')$ , where  $\lim_{\delta \to 0} H_{\delta}(x,\theta') = 0$ , and, for the true value  $\theta_0 \in \Theta$ ,  $\lim_{\delta \to 0} \int_{\mathcal{X}} H_{\delta}(x,\theta') f(x|\theta_0) d\mu = 0$ .
- (A5) If  $\Theta$  is not bounded, then for  $\theta_0 \in \Theta$  and sufficiently large  $\Delta$ , we have  $\log f(x|\theta) \log f(x|\theta_0) < K_{\Delta}(x,\theta_0)$ , whenever  $|\theta| > \Delta$ , where  $\lim_{\Delta \to \infty} \int_{\mathcal{X}} K_{\Delta}(x,\theta_0) f(x|\theta_0) d\mu < 0$ .
- (B1)  $\log f(x|\theta)$  is twice differentiable with respect to  $\theta$  in some neighborhood of  $\theta_0$ .
- (B2) Let  $J(\theta_0) = \int_{\mathcal{X}} f_0(\frac{\partial \log f_0}{\partial \theta_0})^2 d\mu$ , where  $f_0$  denotes  $f(x|\theta_0)$ . Then  $0 < J(\theta_0) < \infty$ .
- (B3)  $\int_{\mathcal{X}} \frac{\partial f_0}{\partial \theta_0} d\mu = \int_{\mathcal{X}} \frac{\partial^2 f_0}{\partial \theta_0^2} d\mu = 0.$
- (B4) If  $|\theta \theta_0| < \delta$ , where  $\delta$  is sufficiently small, then  $|\frac{\partial^2}{\partial \theta^2} \log f(x|\theta) \frac{\partial^2}{\partial \theta_0^2} \log f(x|\theta_0)| < M_{\delta}(x, \delta_0)$ , where  $\lim_{\delta \to 0} \int_{\mathcal{X}} M_{\delta}(x, \theta_0) f(x|\theta_0) d\mu = 0$ .

The following results from Walker (1969) (Theorem 1 and eq. 24) are needed to prove our results:

**Lemma A.1.** Under conditions (A1)-(A5) and (B1)-(B4), if there is no change-point in the interval (a, b] and the true value of parameter within this segment is  $\theta_0$ , then as  $n_{(a,b]} \to \infty$ ,

(i) Let  $N_0(\delta) = \{\theta : |\theta - \theta_0| < \delta\}$  be a neighborhood of  $\theta_0$  contained in  $\Theta$ , the parameter space, there exists a positive number  $k_{\theta_0}(\delta)$ , depending on  $\theta_0$  and  $\delta$ , such that

$$\lim_{n_{(a,b]}\to\infty} P[\sup_{\theta\notin N_0(\delta)} n_{(a,b]}^{-1}\{l_{(a,b]}(\theta) - l_{(a,b]}(\theta_0)\} < -k_{\theta_0}(\delta)] = 1;$$

(*ii*)  $(n_{(a,b]}\hat{\sigma}^2_{(a,b]})^{-1} \xrightarrow{P} J(\theta_0);$ (*iii*)  $l_{(a,b]}(\theta_0) - l_{(a,b]}(\hat{\theta}_{(a,b]}) = O_p(1);$ (*iv*)  $(p_{(a,b]}(\hat{\theta}_{(a,b]}) \hat{\sigma}_{(a,b]})^{-1} D(\boldsymbol{x}_{(a,b]}|\alpha) \xrightarrow{P} (2\pi)^{1/2} \pi(\theta_0|\alpha).$ 

The following two lemmas are also needed:

**Lemma A.2.** Assume regularity conditions 1)- 4). Let  $a_n$  be a sequence with each element lying between two true change-points  $a_n \in [\tau_j^0, \tau_{j+1}^0]$ 

(i) If  $n_{(\tau_j^0, a_n]} \to \infty$  and  $n_{(a_n, \tau_{j+1}^0]} \to \infty$ , then

$$\frac{D(\boldsymbol{x}_{(\tau_{j}^{0},a_{n}]}|\alpha)D(\boldsymbol{x}_{(a_{n},\tau_{j+1}^{0}]}|\alpha)}{D(\boldsymbol{x}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}|\alpha)} = O_{p}\left(\sqrt{\frac{n_{(\tau_{j}^{0},\tau_{j+1}^{0}]}}{n_{(\tau_{j}^{0},a_{n}]}n_{(a_{n},\tau_{j+1}^{0}]}}}\right).$$

(ii) If  $\limsup n_{(\tau_j^0,a_n]} < \infty$  and  $n_{(a_n,\tau_{j+1}^0]} \to \infty$ , then

$$\frac{D(\boldsymbol{x}_{(\tau_{j}^{0},a_{n}]}|\alpha)D(\boldsymbol{x}_{(a_{n},\tau_{j+1}^{0}]}|\alpha)}{D(\boldsymbol{x}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}|\alpha)} = O_{p}(1).$$

(iii) If  $n_{(\tau_j^0,a_n]} \to \infty$  and  $\limsup n_{(a_n,\tau_{j+1}^0]} < \infty$ , then

$$\frac{D(\boldsymbol{x}_{(\tau_{j}^{0},a_{n}]}|\alpha)D(\boldsymbol{x}_{(a_{n},\tau_{j+1}^{0}]}|\alpha)}{D(\boldsymbol{x}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}|\alpha)} = O_{p}(1).$$

**PROOF of Lemma A.2.** Let  $\theta_{j+1}$  denote the true parameter of the segment.

(i) By Lemma A.1(iv),  $n_{(\tau_i^0, a_n]} \to \infty$  and  $n_{(a_n, \tau_{i+1}^0]} \to \infty$  imply

$$\frac{D(\boldsymbol{x}_{(\tau_{j}^{0},a_{n}]}|\alpha)D(\boldsymbol{x}_{(a_{n},\tau_{j+1}^{0}]}|\alpha)}{D(\boldsymbol{x}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}|\alpha)}$$

$$= O_{p}\left(\frac{p_{(\tau_{j}^{0},a_{n}]}(\hat{\theta}_{(\tau_{j}^{0},a_{n}]})\hat{\sigma}_{(\tau_{j}^{0},a_{n}]} \times p_{(a_{n},\tau_{j+1}^{0}]}(\hat{\theta}_{(a_{n},\tau_{j+1}^{0}]})\hat{\sigma}_{(a_{n},\tau_{j+1}^{0}]}}{p_{(\tau_{j}^{0},\tau_{j+1}^{0}]}(\hat{\theta}_{(\tau_{j}^{0},\tau_{j+1}^{0}]})\hat{\sigma}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}}\right).$$

Lemma A.1(iii) tells us

$$\begin{array}{rcl} & \frac{p_{(\tau_{j}^{0},a_{n}]}(\hat{\theta}_{(\tau_{j}^{0},a_{n}]})p_{(a_{n},\tau_{j+1}^{0}]}(\hat{\theta}_{(a_{n},\tau_{j+1}^{0}]})}{p_{(\tau_{j}^{0},\tau_{j+1}^{0}]}(\hat{\theta}_{(\tau_{j}^{0},\tau_{j+1}^{0}]})} \\ & = & \frac{p_{(\tau_{j}^{0},a_{n}]}(\hat{\theta}_{(\tau_{j}^{0},a_{n}]})[p_{(\tau_{j}^{0},a_{n}]}(\theta_{j+1})]^{-1}p_{(a_{n},\tau_{j+1}^{0}]}(\hat{\theta}_{(a_{n},\tau_{j+1}^{0}]})[p_{(a_{n},\tau_{j+1}^{0}]}(\theta_{j+1})]^{-1}}{p_{(\tau_{j}^{0},\tau_{j+1}^{0}]}(\hat{\theta}_{(\tau_{j}^{0},\tau_{j+1}^{0}]})[p_{(\tau_{j}^{0},\tau_{j+1}^{0}]}(\theta_{j+1})]^{-1}} \\ & = & O_{p}(1) \end{array}$$

Note also that

$$\begin{array}{lll} \frac{\hat{\sigma}_{(\tau_{j}^{0},a_{n}]}\hat{\sigma}_{(a_{n},\tau_{j+1}^{0}]}}{\hat{\sigma}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}} & = & \frac{\hat{\sigma}_{(\tau_{j}^{0},a_{n}]}\sqrt{n_{(\tau_{j}^{0},a_{n}]}}\hat{\sigma}_{(a_{n},\tau_{j+1}^{0}]}\sqrt{n_{(a_{n},\tau_{j+1}^{0}]}}{\hat{\sigma}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}\sqrt{n_{(\tau_{j}^{0},\tau_{j+1}^{0}]}}}{\sqrt{n_{(\tau_{j}^{0},\tau_{j+1}^{0}]}}}\sqrt{\frac{n_{(\tau_{j}^{0},a_{n}]}n_{(a_{n},\tau_{j+1}^{0}]}}{n_{(\tau_{j}^{0},a_{n}]}n_{(a_{n},\tau_{j+1}^{0}]}}}}{\frac{P}{\sqrt{J^{-1}(\theta_{j+1})}}\sqrt{\frac{n_{(\tau_{j}^{0},a_{n}]}n_{(a_{n},\tau_{j+1}^{0}]}}{n_{(\tau_{j}^{0},a_{n}]}n_{(a_{n},\tau_{j+1}^{0}]}}}}. \end{array}$$

by Lemma A.1(ii). The desired result follows.

(ii) If  $\limsup n_{(\tau_j^0, a_n]} < \infty$  and  $n_{(a_n, \tau_{j+1}^0]} \to \infty$ , then similar argument applies to  $D(\boldsymbol{x}_{(a_n, \tau_{j+1}^0]} | \alpha)$ and  $D(\boldsymbol{x}_{(\tau_j^0, \tau_{j+1}^0]} | \alpha)$  gives

$$\frac{D(\boldsymbol{x}_{(\tau_{j}^{0},a_{n}]}|\alpha)D(\boldsymbol{x}_{(a_{n},\tau_{j+1}^{0}]}|\alpha)}{D(\boldsymbol{x}_{(\tau_{j}^{0},\tau_{j+1}^{0}]}|\alpha)} = O_{p}\left(\frac{D(\boldsymbol{x}_{(\tau_{j}^{0},a_{n}]}|\alpha)}{p_{(\tau_{j}^{0},a_{n}]}(\theta_{j+1})}\sqrt{\frac{n_{(\tau_{j}^{0},\tau_{j+1}^{0}]}}{n_{(a_{n},\tau_{j+1}^{0}]}}}\right)$$

$$\begin{split} &\lim \sup n_{(\tau_j^0,a_n]} < \infty \text{ implies that } n_{(\tau_j^0,a_n]} \text{ is bounded, say by } B < \infty, \text{ for all } n. \text{ This implies } \\ &n_{(\tau_j^0,\tau_{j+1}^0]}/n_{(a_n,\tau_{j+1}^0]} \to 1. \text{ Furthermore, note that for all } \theta, p_{(\tau_j^0,a_n]}(\theta) \text{ is a product of up to } B \text{ i.i.d. random variables and } D(\boldsymbol{x}_{(\tau_j^0,a_n]}|\alpha) = \int_{\Theta} p_{(\tau_j^0,a_n]}(\theta)\pi(\theta|\alpha)d\theta. B \text{ is finite. } D(\boldsymbol{x}_{(\tau_j^0,a_n]}|\alpha)/p_{(\tau_j^0,a_n]}(\theta_{j+1}) \text{ is, therefore, bounded in probability. The desired result thus follows. } \Box \end{split}$$

The proof of (iii) is essentially identical to that of (ii).

**Lemma A.3.** Assume regularity conditions 1)- 4). Let  $(a_n, b_n]$  be a sequence of intervals that contains one and only one true change-point  $\tau^0$ .

(i) If  $n_{(a_n,\tau^0]} \to \infty$  and  $n_{(\tau^0,b_n]} \to \infty$ , then

$$\frac{D(\boldsymbol{x}_{(a_n,b_n]}|\alpha)}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} \xrightarrow{P} 0.$$
(A.1)

(ii) If  $\limsup n_{(a_n,\tau^0]} < \infty$  and  $n_{(\tau^0,b_n]} \to \infty$ , then

$$\frac{D(\boldsymbol{x}_{(a_n,b_n]}|\alpha)}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} = O_p(1).$$
(A.2)

(iii) If  $n_{(a_n,\tau^0]} \to \infty$  and  $\limsup n_{(\tau^0,b_n]} < \infty$ , then

$$\frac{D(\boldsymbol{x}_{(a_n,b_n]}|\alpha)}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} = O_p(1).$$
(A.3)

**PROOF of Lemma A.3.** Let  $\theta_1$  and  $\theta_2$  be the two segment-parameters before and after  $\tau^0$ . By definition,  $D(\boldsymbol{x}_{(a_n,b_n]}|\alpha) = \int_{\Theta} p_{(a_n,\tau^0]}(\theta)p_{(\tau^0,b_n]}(\theta)\pi(\theta|\alpha)d\theta$ . Let  $N_1(\delta)$  and  $N_2(\delta)$  be disjoint neighborhoods of  $\theta_1$  and  $\theta_2$ . We split  $D(\boldsymbol{x}_{(a_n,b_n]}|\alpha)$  into three integrals,  $I_1, I_2$  and  $I_3$ , taken respectively over the sets  $N_1(\delta)$ ,  $N_2(\delta)$  and  $\Theta - N_1(\delta) - N_2(\delta)$ .

(i) If  $n_{(a_n,\tau^0]} \to \infty$  and  $n_{(\tau^0,b_n]} \to \infty$ , then for the first integral, we can write

$$\begin{split} I_{1} &= \int_{N_{1}(\delta)} p_{(a_{n},\tau^{0}]}(\theta) p_{(\tau^{0},b_{n}]}(\theta) \pi(\theta|\alpha) d\theta \\ &= p_{(\tau^{0},b_{n}]}(\hat{\theta}_{(\tau^{0},b_{n}]}) \,\hat{\sigma}_{(\tau^{0},b_{n}]} \exp[l_{(\tau^{0},b_{n}]}(\theta_{2}) - l_{(\tau^{0},b_{n}]}(\hat{\theta}_{(\tau^{0},b_{n}]})] \\ &\times \int_{N_{1}(\delta)} \hat{\sigma}_{(\tau^{0},b_{n}]}^{-1} \exp\{l_{(\tau^{0},b_{n}]}(\theta) - l_{(\tau^{0},b_{n}]}(\theta_{2})\} p_{(a_{n},\tau^{0}]}(\theta) \pi(\theta|\alpha) d\theta. \end{split}$$

According to Lemma A.1(i), the integral on the above right-hand side is less than

$$\begin{aligned} \hat{\sigma}_{(\tau^{0},b_{n}]}^{-1} \exp(-n_{(\tau^{0},b_{n}]}k_{2}(\delta)) \int_{N_{1}(\delta)} p_{(a_{n},\tau^{0}]}(\theta)\pi(\theta|\alpha)d\theta \\ &\leq \hat{\sigma}_{(\tau^{0},b_{n}]}^{-1} \exp(-n_{(\tau^{0},b_{n}]}k_{2}(\delta)) \int_{\Theta} p_{(a_{n},\tau^{0}]}(\theta)\pi(\theta|\alpha)d\theta \\ &= \{n_{(\tau^{0},b_{n}]}\hat{\sigma}_{(\tau^{0},b_{n}]}^{2}\}^{-1/2} n_{(\tau^{0},b_{n}]}^{1/2} \exp(-n_{(\tau^{0},b_{n}]}k_{2}(\delta)) D(\boldsymbol{x}_{(a_{n},\tau^{0}]}|\alpha) \end{aligned}$$

with probability tending to 1. We know from Lemma A.1(ii), (iii) and (iv) that  $n_{(\tau^0, b_n]} \to \infty$  implies

$$\begin{split} &[n_{(\tau^{0},b_{n}]}\hat{\sigma}^{2}_{(\tau^{0},b_{n}]}]^{-1/2} \xrightarrow{P} J^{1/2}(\theta_{2}) \\ &\exp\{l_{(\tau^{0},b_{n}]}(\theta_{2}) - l_{(\tau^{0},b_{n}]}(\hat{\theta}_{(\tau^{0},b_{n}]})\} = O_{p}(1), \\ &[p_{(\tau^{0},b_{n}]}(\hat{\theta}_{(\tau^{0},b_{n}]}) \hat{\sigma}_{(\tau^{0},b_{n}]}]^{-1} D(\boldsymbol{x}_{(\tau^{0},b_{n}]}|\alpha) \xrightarrow{P} (2\pi)^{1/2} \pi(\theta_{2}|\alpha). \end{split}$$

It follows that

$$\frac{I_1}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} = O_p(n_{(\tau^0,b_n]}^{1/2}\exp\{-n_{(\tau^0,b_n]}k_2(\delta)\}) \xrightarrow{P} 0.$$
(A.4)

Identical argument applied to  $I_2$ , the integral over  $N_2(\delta)$ , together with  $n_{(a_n,\tau^0]} \to \infty$ , gives

$$\frac{I_2}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} = O_p(n_{(a_n,\tau^0]}^{1/2}\exp\{-n_{(a_n,\tau^0]}k_1(\delta)\}) \xrightarrow{P} 0.$$

For the integral  $I_3$ , we apply the same argument, but we note that since the region  $\Theta - N_1(\delta) - N_2(\delta)$ contains neither the neighborhood of  $\theta_1$  nor the neighborhood of  $\theta_2$ ,

$$\frac{I_3}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} = O_p((n_{(a_n,\tau^0]}n_{(\tau^0,b_n]})^{1/2}\exp\{-n_{(a_n,\tau^0]}k_1(\delta) - n_{(\tau^0,b_n]}k_2(\delta)\}),$$

which converges to zero even faster. This proves (A.1).

(ii)  $n_{(\tau^0, b_n]} \to \infty$  alone gives (A.4) and that

$$\frac{I_3}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} = O_p(n_{(\tau^0,b_n]}^{1/2}\exp\{-n_{(\tau^0,b_n]}k_2(\delta)\}) \xrightarrow{P} 0$$

Let us next consider  $I_2$ . If  $\limsup n_{(a_n,\tau^0]} < \infty$ , then we know that  $n_{(a_n,\tau^0]}$  is bounded, say by  $B < \infty$ , for all n.

$$I_{2} = \int_{N_{2}(\delta)} p_{(a_{n},\tau^{0}]}(\theta) p_{(\tau^{0},b_{n}]}(\theta)\pi(\theta|\alpha)d\theta$$
  
=  $p_{(a_{n},\tau^{0}]}(\theta_{2}) \int_{N_{2}(\delta)} \exp\{l_{(a_{n},\tau^{0}]}(\theta) - l_{(a_{n},\tau^{0}]}(\theta_{2})\}p_{(\tau^{0},b_{n}]}(\theta)\pi(\theta|\alpha)d\theta$ 

Condition (A4) tells us that  $|l_{(a_n,\tau^0]}(\theta) - l_{(a_n,\tau^0]}(\theta_2)| \leq \sum H_{\delta}(x_i,\theta_2)$ , where the sum is over  $t_i \in (a_n,\tau^0]$ , which has up to B terms. It follows that

$$I_{2} \leq p_{(a_{n},\tau^{0}]}(\theta_{2}) \exp\{\sum H_{\delta}(x_{i},\theta_{2})\} \int_{N_{2}(\delta)} p_{(\tau^{0},b_{n}]}(\theta)\pi(\theta|\alpha)d\theta$$
$$\leq p_{(a_{n},\tau^{0}]}(\theta_{2}) \exp\{\sum H_{\delta}(x_{i},\theta_{2})\} D(\boldsymbol{x}_{(\tau^{0},b_{n}]}|\alpha).$$

Thus

$$\frac{I_2}{D(\boldsymbol{x}_{(a_n,\tau^0]}|\alpha)D(\boldsymbol{x}_{(\tau^0,b_n]}|\alpha)} \le \frac{p_{(a_n,\tau^0]}(\theta_2)\exp\{\sum H_{\delta}(x_i,\theta_2)\}}{\int_{\Theta} p_{(a_n,\tau^0]}(\theta)\pi(\theta|\alpha)d\theta}$$
(A.5)

Note that  $p_{(a_n,\tau^0]}(\theta)$  is a product of up to *B* i.i.d. random variables and  $\sum H_{\delta}(x_i,\theta_2)$  is a sum of up to *B* i.i.d. random variables. *B* is finite. The right hand side of (A.5) is, therefore, bounded in probability. This gives (A.2).  $\Box$ 

The proof of (iii) is essentially identical to that of (ii).

**PROOF of Lemma 3.1.** First, let us consider the case of m = 1.

$$\frac{P(\boldsymbol{x}|\{0,\tau_1,1\})}{P(\boldsymbol{x}|\{0,1\})} = \frac{D(\boldsymbol{x}_{(0,\tau_1]}|\alpha)D(\boldsymbol{x}_{(\tau_1,1]}|\alpha)}{D(\boldsymbol{x}_{(0,1]}|\alpha)}.$$

Lemma A.2(i) tells us that it is  $O_p(n_{(0,1]}^{1/2}/(n_{(0,\tau_1]}n_{(\tau_1,1]})^{1/2})$ . But  $n_{(0,\tau_1]}n_{(\tau_1,1]}/\{n^2C_{(0,\tau_1]}C_{(\tau_1,1]}\}\xrightarrow{P} 1$  by regularity condition 3, it follows that

$$\frac{P(\boldsymbol{x}|\{0,\tau_1,1\})}{P(\boldsymbol{x}|\{0,1\})} = O_p\left(1/\sqrt{nC_{(0,\tau_1]}C_{(\tau_1,1]}}\right) = O_p(1/\sqrt{n\Delta_{\tau}}).$$

Next, suppose that the lemma holds for all  $m \leq M$ , (M > 1). Then for m = M + 1,

$$\frac{P(\boldsymbol{x}|\{0,\tau_1,\cdots,\tau_M,1\})}{P(\boldsymbol{x}|\{0,1\})} = \frac{P(\boldsymbol{x}|\{0,\tau_2,\cdots,\tau_M,1\})}{P(\boldsymbol{x}|\{0,1\})} \frac{P(\boldsymbol{x}|\{0,\tau_1,\cdots,\tau_M,1\})}{P(\boldsymbol{x}|\{0,\tau_2,\cdots,\tau_M,1\})}.$$

By the induction assumption,  $P(\boldsymbol{x}|\{0,\tau_2,\cdots,\tau_M,1\})/P(\boldsymbol{x}|\{0,1\}) \xrightarrow{P} 0$ . Note that

$$\frac{P(\boldsymbol{x}|\{0,\tau_1,\cdots,\tau_M,1\})}{P(\boldsymbol{x}|\{0,\tau_2,\cdots,\tau_M,1\})} = \frac{D(\boldsymbol{x}_{(0,\tau_1]}|\alpha)D(\boldsymbol{x}_{(\tau_1,\tau_2]}|\alpha)}{D(\boldsymbol{x}_{(0,\tau_2]}|\alpha)}$$

Lemma A.2(i) again tells us that the above expression converges to 0 in probability. Therefore, the lemma is also true for m = M + 1:  $P(\boldsymbol{x}|\{0, \tau_1, \cdots, \tau_M, 1\})/P(\boldsymbol{x}|\{0, 1\}) = O_p(1/\sqrt{n\Delta_{\tau}})$ .  $\Box$ 

**PROOF of Lemma 3.2.** We need only to prove this lemma for  $m_0 = 2$ ; the rest can be proved using the same mathematical induction technique as in the proof of Lemma 3.1. We have

$$\frac{P(\boldsymbol{x}|\{0,1\})}{P(\boldsymbol{x}|\{0,\tau_1^0,1\})} = \frac{D(\boldsymbol{x}_{(0,\tau_1^0)}|\alpha)}{D(\boldsymbol{x}_{(0,\tau_1^0)}|\alpha)D(\boldsymbol{x}_{(\tau_1^0,1]}|\alpha)}.$$

Taking  $a_n \equiv 0$  and  $b_n \equiv 1$  in Lemma A.3(i), we know from its proof that

$$\frac{D(\boldsymbol{x}_{(0,1]}|\alpha)}{D(\boldsymbol{x}_{(0,\tau_1^0)}|\alpha)D(\boldsymbol{x}_{(\tau_1^0,1]}|\alpha)} = O_p(n_{(0,\tau_1^0)}^{1/2}\exp\{-n_{(0,\tau_1^0)}k_1(\delta)\}) + O_p(n_{(\tau_1^0,1]}^{1/2}\exp\{-n_{(\tau_1^0,1]}k_2(\delta)\}).$$

Condition 3 suggests that  $O_p(\sqrt{n_{(\tau_1^0,1]}} \exp\{-n_{(\tau_1^0,1]}k_2(\delta)\}) = O_p(\sqrt{n\Delta_0} \exp(-cn\Delta_0))$ , for positive constant c, and so does  $O_p(\sqrt{n_{(0,\tau_1^0)}} \exp\{-n_{(0,\tau_1^0)}k_1(\delta)\})$ . We thus prove the lemma for  $m_0 = 2$ .  $\Box$ 

**PROOF of Theorem 3.3.** Our proof consists of three steps. Step 1. Let  $\mathcal{E}_1$  be the event that there is at least one true change-point  $\tau_j^0$   $(0 \le j \le m_0)$  that no estimated change-point is within  $\overline{\Delta}/2$  of it, i.e.,  $\hat{\tau}_i \notin (\tau_j^0 - \overline{\Delta}/2, \tau_j^0 + \overline{\Delta}/2)$  for all *i*. We will show that the probability of  $\mathcal{E}_1$  goes to 0.

Suppose  $\hat{\tau}$  is such an estimate. Let  $\hat{\tau}_i$  and  $\hat{\tau}_{i+1}$  be the estimated change-points that sandwich  $\tau_j^0$ :  $\hat{\tau}_i < \tau_j^0 < \hat{\tau}_{i+1}$ . Let  $\tau_{j-l}^0 < \cdots < \tau_{j+r}^0$  be the sequence of true change-points  $(l, r \ge 0)$  that are between  $\hat{\tau}_i$  and  $\hat{\tau}_{i+1}$ 

$$\tau_{j-l-1}^0 < \hat{\tau}_i < \tau_{j-l}^0 < \ldots < \tau_{j+r}^0 < \hat{\tau}_{i+1} < \tau_{j+r+1}^0$$

Consider an alternative choice of change-points

$$\tilde{\boldsymbol{\tau}} = \{ \hat{\tau}_0, \hat{\tau}_1, \cdots, \hat{\tau}_i, \tau_{j-l}^0, \dots, \tau_{j+k}^0, \hat{\tau}_{i+1}, \cdots, \hat{\tau}_{\hat{m}} \},\$$

which is formed by inserting  $\tau_{j-l}^0 < \cdots < \tau_{j+r}^0$  into  $\hat{\tau}$ . It is clear that

$$\frac{P(\boldsymbol{x}|\hat{\boldsymbol{\tau}})}{P(\boldsymbol{x}|\tilde{\boldsymbol{\tau}})} = \frac{D(\boldsymbol{x}_{(\hat{\tau}_{i},\hat{\tau}_{i+1}]}|\alpha)}{D(\boldsymbol{x}_{(\hat{\tau}_{i},\tau_{j-l}]}|\alpha) \times D(\boldsymbol{x}_{(\tau_{j-l}^{0},\tau_{j-l+1}^{0}]}|\alpha) \times \cdots \times D(\boldsymbol{x}_{(\tau_{j+k-1}^{0},\tau_{j+k}^{0}]}|\alpha) \times D(\boldsymbol{x}_{(\tau_{j+k}^{0},\hat{\tau}_{i+1}]}|\alpha)}$$

Since  $n_{(\hat{\tau}_i, \tau_j^0]} \to \infty$ ,  $n_{(\tau_j^0, \hat{\tau}_{i+1}]} \to \infty$  and  $n_{(\tau_k^0, \tau_{k+1}^0]} \to \infty$  (for any k) by condition 5, it follows from Lemma A.3 that the ratio  $P(\boldsymbol{x}|\hat{\boldsymbol{\tau}})/P(\boldsymbol{x}|\tilde{\boldsymbol{\tau}})$  would go to zero in probability. Another way to look at it is to think of  $\tilde{\boldsymbol{\tau}}$  as being created by inserting the true change-points one at a time from the left. The first and last insertions would have probability contribution of  $O_p(1)$  by Lemma A.3, while the middle ones would have probability contribution  $o_p(1)$  by Lemma 3.2. Therefore, the probability of having such an estimate  $\hat{\tau}$  goes to zero, i.e., the probability of  $\mathcal{E}_1$  goes to zero. This in fact proves equation (3.1), since  $\overline{\Delta}/2 \to 0$  by condition 5.

Step 2. The previous step tells us that, with probability going to one, for each true change-point  $\tau_j^0$ , there would be at least one estimated change-point  $\hat{\tau}_i$  such that  $|\hat{\tau}_i - \tau_j^0| < \overline{\Delta}/2$ . On the other hand, since  $\hat{\tau}_{i+1} - \hat{\tau}_i \geq \overline{\Delta}$  by the definition, we know that there cannot be two estimated change-point within  $(\tau_j^0 - \overline{\Delta}/2, \tau_j^0 + \overline{\Delta}/2)$ . Hence, with probability going to one, for each true change-point  $\tau_j^0$ , there would be one and only one estimated change-point  $\hat{\tau}_i$  such that  $|\hat{\tau}_i - \tau_j^0| < \overline{\Delta}/2$ .

Step 3. In order to establish  $\hat{m} \xrightarrow{P} m_0$ , it remains to show that, with probability going to one, the union of  $\bigcup_j (\tau_j^0 - \overline{\Delta}/2, \tau_j^0 + \overline{\Delta}/2)$  contains all the estimated change-points. Suppose  $\hat{\tau}_i$  is outside the union. Let  $\tau_j^0$  and  $\tau_{j+1}^0$  be the adjacent true change-points that sandwich  $\hat{\tau}_i: \tau_j^0 < \hat{\tau}_i < \tau_{j+1}^0$ . We must have  $\hat{\tau}_i - \tau_j^0 \ge \overline{\Delta}/2$  and  $\tau_{j+1}^0 - \hat{\tau}_i \ge \overline{\Delta}/2$ . From Steps 1 and 2, we know that with probability going to one, there are two estimated change-points of which one is within  $\overline{\Delta}/2$  of  $\tau_j^0$  and the other is within  $\overline{\Delta}/2$  of  $\tau_{j+1}^0$ . Let  $\hat{\tau}_{i-l} < \cdots < \hat{\tau}_{i+r}$  be the sequence of estimated change-points  $(l, r \ge 0)$ that are between  $\tau_j^0$  and  $\tau_{j+1}^0$ :

$$\tau_j^0 < \hat{\tau}_{i-l} < \dots < \hat{\tau}_{i+r} < \tau_{j+1}^0$$

Consider the following alternative change-points:

$$\tilde{\boldsymbol{\tau}} := \hat{\boldsymbol{\tau}} - \{\hat{\tau}_{i-l}, \dots, \hat{\tau}_{i+r}\} = \{\tau_0, \tau_1, \cdots, \tau_{i-l-1}, \tau_{i+r+1}, \dots, \tau_m\}.$$

We can think of  $\tilde{\tau}$  as being created by deleting from  $\hat{\tau}$  the estimated change-points one at a time starting from  $\hat{\tau}_{i-l}$ . According to Lemma A.2, deleting  $\hat{\tau}_{i-l}$  and  $\hat{\tau}_{i+r}$  would have probability contribution of either  $O_p(1)$  or  $o_p(1)$ , while deleting the middle ones would have probability contribution of  $o_p(1)$ , since  $\hat{\tau}_{k+1} - \hat{\tau}_k \geq \overline{\Delta}$  by the definition and  $n\overline{\Delta} \to \infty$ . It follows that the ratio  $P(\boldsymbol{x}|\hat{\boldsymbol{\tau}})/P(\boldsymbol{x}|\tilde{\boldsymbol{\tau}})$ would go to zero in probability. Therefore, the probability of having a  $\hat{\tau}_i$  outside the union of  $\bigcup_j (\tau_j^0 - \overline{\Delta}/2, \tau_j^0 + \overline{\Delta}/2)$  goes to zero. This concludes our proof.  $\Box$ 

**PROOF of Corollary 3.4.** Since in the proof of Theorem 3.3 the only place that  $\pi(\theta|\alpha)$  appears is in Lemma A.1 (iv), for the proof we only need to show that

$$(p_{(a,b]}(\hat{\theta}_{(a,b]})\hat{\sigma}_{(a,b]})^{-1}D(x_{(a,b]}|\hat{\alpha}_n) \xrightarrow{P} (2\pi)^{1/2}\pi(\theta_0|\alpha^*).$$
(A.6)

To do so, let  $N(\delta)$  be a neighborhood of  $\theta_1$ . Then, we have

$$D(x_{(a,b]}|\hat{\alpha}_n) = \int_{N(\delta)} p_{(a,b]}(\theta)\pi(\theta|\hat{\alpha}_n)d\theta + \int_{\Theta - N(\delta)} p_{(a,b]}(\theta)\pi(\theta|\hat{\alpha}_n)d\theta.$$

For the first term, since  $\pi(\theta|\alpha)$  is continuous at  $\alpha^*$ , and  $\hat{\alpha}_n \xrightarrow{P} \alpha^*$ , we have,

$$\int_{N(\delta)} p_{(a,b]}(\theta) \pi(\theta | \hat{\alpha}_n) d\theta = \int_{N(\delta)} p_{(a,b]}(\theta) \frac{\pi(\theta | \hat{\alpha}_n)}{\pi(\theta | \alpha^*)} \pi(\theta | \alpha^*) d\theta = (1 - o_p(1)) \int_{N(\delta)} p_{(a,b]}(\theta) \pi(\theta | \alpha^*) d\theta.$$

For the second term, by Lemma A.1 (i) and a similar analogue to Lemma A.3, one could show that

$$(p_{(a,b]}(\hat{\theta}_{(a,b]})\hat{\sigma}_{(a,b]})^{-1}\int_{\Theta-N(\delta)}p_{(a,b]}(\theta)\pi(\theta|\hat{\alpha}_n)d\theta = o_p(1).$$

Similarly, we have

$$(p_{(a,b]}(\hat{\theta}_{(a,b]})\hat{\sigma}_{(a,b]})^{-1}\int_{\Theta-N(\delta)}p_{(a,b]}(\theta)\pi(\theta|\alpha^*)d\theta = o_p(1).$$

Combining them, we know that replacing  $\hat{\alpha}_n$  by  $\alpha^*$  does not change the asymptotics of the left hand side of (A.6), that is,

$$(p_{(a,b]}(\hat{\theta}_{(a,b]})\hat{\sigma}_{(a,b]})^{-1}D(x_{(a,b]}|\hat{\alpha}_n) = (p_{(a,b]}(\hat{\theta}_{(a,b]})\hat{\sigma}_{(a,b]})^{-1}D(x_{(a,b]}|\alpha^*) + o_p(1) = (2\pi)^{1/2}\pi(\theta_0|\alpha^*) + o_p(1)$$

This completes the proof.  $\Box$ 

## References

 WALKER, A. M. (1969). On the asymptotic behaviour of posterior distributions. J. Roy. Statist. Soc., B, 31, 80-88.